# Basic Mechatronics Workshop Module 3: Introduction to PLC

#### LAB-5

PLC Hardware Configure (Power and CPU, Base, Input, Output, Special Module) (Conference of Presentation)

# Dr. Mohamed Abdalbar

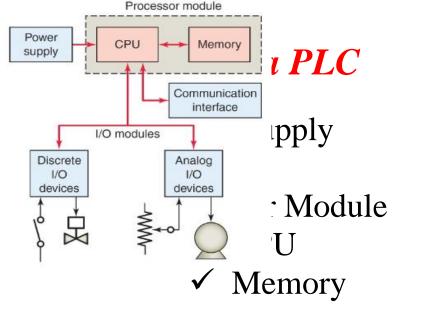
Lecturer, Mechatronics Department, Egyptian-Korean Faculty of Technological Industry and Energy, Beni Suef Technological University Email: <u>mh\_abd2001@yahoo.com</u>

### LAB-5

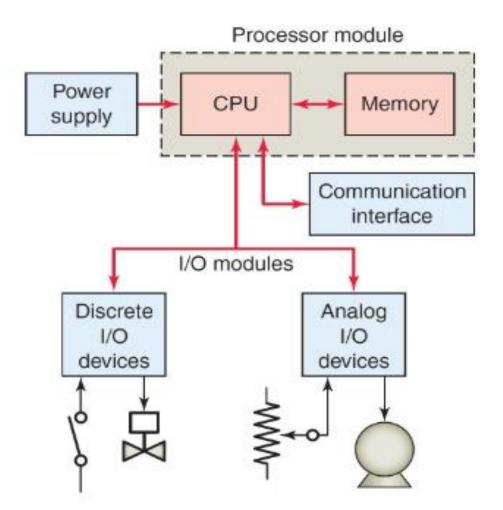
#### PLC Hardware Configure (Power and CPU, Base, Input, Output, Special Module) Objectives (Conference of Presentation)

Upon completion of this chapter, Student should be able to

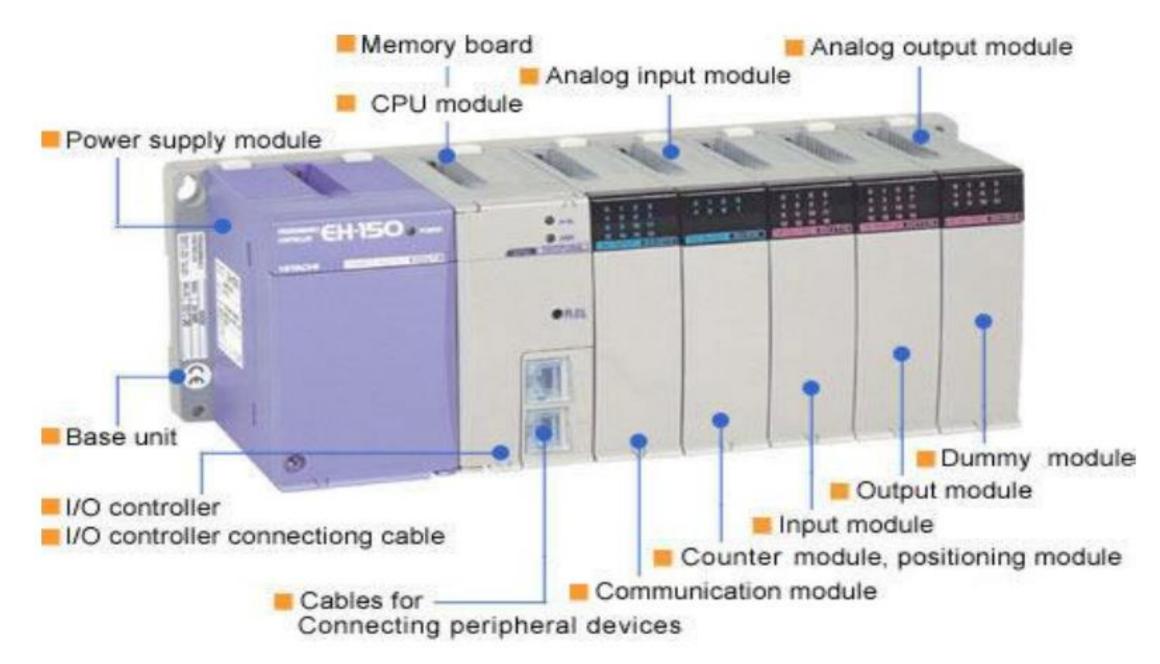
- ✓ Define basic parts of a PLC
- $\checkmark$  Explain the function of power supply in the PLC.
- $\checkmark\,$  Explain the function of CPU (Controller/ Processor) in the PLC.
- $\checkmark\,$  Explain the Input/ Output (I/O) capabilities of PLC.
- $\checkmark\,$  Explain the discrete I/O architecture.
- ✓ Describe Analog I/O PLC module characteristics.
- $\checkmark$  Describe the functions of special module.



- 3. Communication Interface.
  - ✓ HMI Status,
  - ✓ HMI Programming
- 4. I/O Modules
  - ✓ Discrete/Digital Inputs
  - ✓ Analog Inputs
  - ✓ Output Modules



### Basic parts of a PLC



#### **Power Supply**

Usually, PLC power supplies require input from an AC power source; however, some PLCs will accept a DC power source. Those that will accept

Most PLCs, however, require a 120 VAC or 220 VAC power sources, while a few controllers will accept 24 VDC.

Since industrial facilities normally experience fluctuations in line voltage and frequency, a PLC power supply must be able to tolerate a 10 to 15% variation in line voltage conditions.

The first step in estimating the load is to determine how many modules are required and then compute the total current requirement of these modules.



PLC Power Supply (Courtesy: Allen Bradley)

#### CPU (Controller/ Processor)

- Processors are either modular or built into the PLC
- They vary in processing speed and memory options.
- Processor is optimized for high speed control and not general-purpose computing.



Mitsubishi PLC CPU Module



Siemens PLC CPU 315-2DP



**Omron PLC CPU Unit CS1G-CPU44H** 

### **CPU** (Controller/ Processor)

### **CPU Functions:**

1. Executes the operating	RUN
system	• Places
2. Manages memory,	• Runs L
3. Monitors inputs,	• Prevent
4. Evaluates the means for	• Prever
connecting to an external	device to
programming device	
5. Provide system	PROG F
diagnostics with status	• Sets the
LED indicators.	• Prevent
6. It may have a switch for	the ladde
selecting mode of	energize
operation:	• Enables
✓ RUN,	• Preven
✓ PROG	interface
✓ REM	
	REM Po
	<ul> <li>Places t</li> </ul>
	REMote
	mode
	• Allows
	program
	• A 11 outro

- the processor in the Run mode
- adder program and energizes output devices
- ts online program editing in this position
- ents use of programmer/operator interface o change the processor mode

#### Position

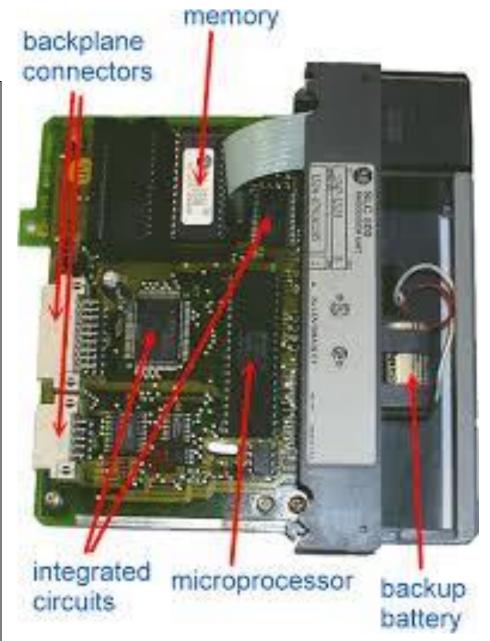
- e processor in the Program mode
- its the processor from scanning or executing er program, and the controller outputs are de-
- s program entry and editing
- nts you from using a programmer/operator e device to change the processor mode

#### osition

the processor in the Remote mode: either the Run, REMote Program, or REMote Test

s you to change the processor mode from a mer/operator interface device

• Allows you to perform online program editing



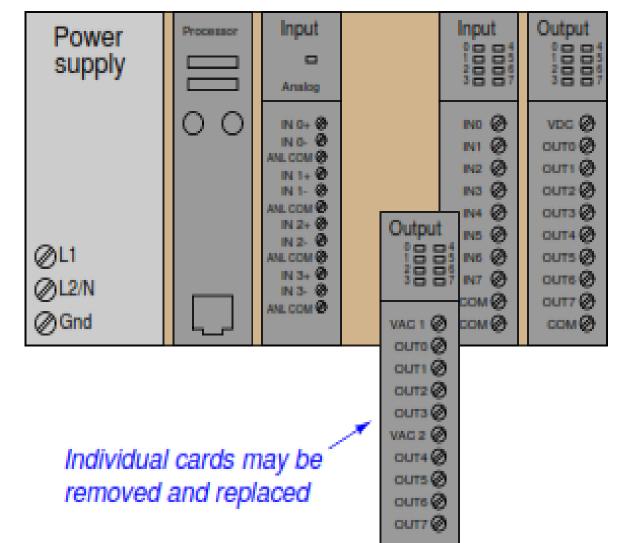
### Input/ Output (I/O) capabilities

#### Monolithic PLC

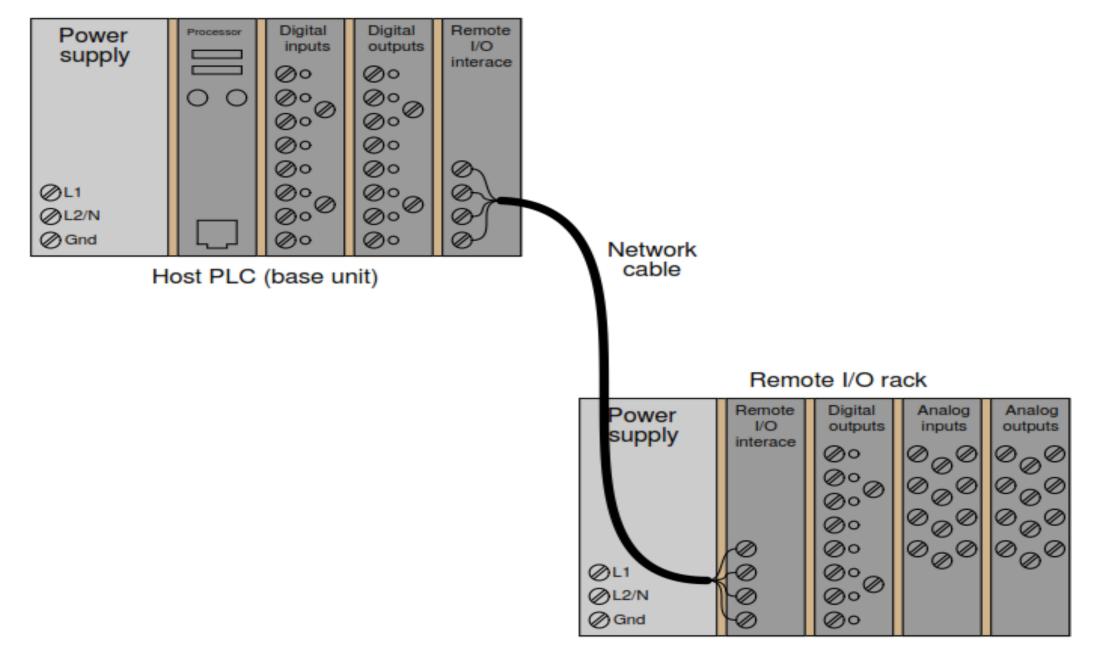
⊘∘x1 Ø		Ø Y10Ø
ذX2		Y2 0⊘
ذX3		¥3 0⊘
ذX4	PLC	¥4 0⊘
ذx5		Y2 0⊘
ذx6		¥6 0⊘
⊘Common	Programming	Source Ø

All I/O is fixed in one PLC unit

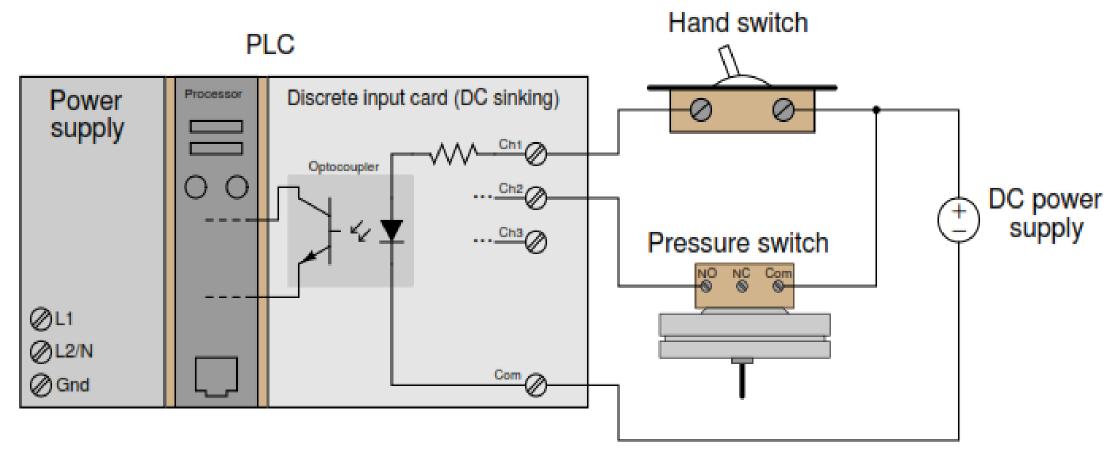
#### Modular ("rack-based") PLC



#### Input/ Output (I/O) capabilities



#### Discrete I/O



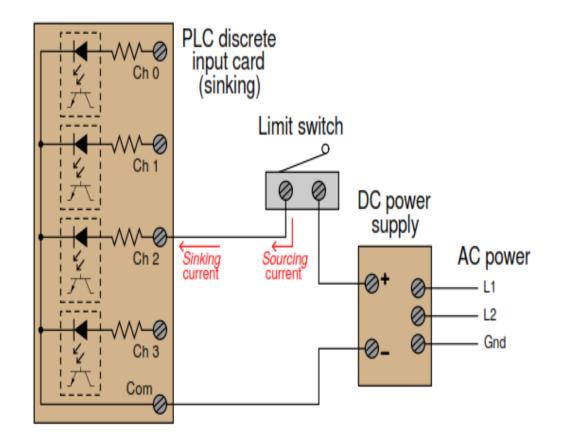
Energizing an input channel lights the LED inside the optocoupler, turning on the phototransistor, sending a "high" signal to the PLC's microprocessor, setting (1) that bit in the PLC's input register.

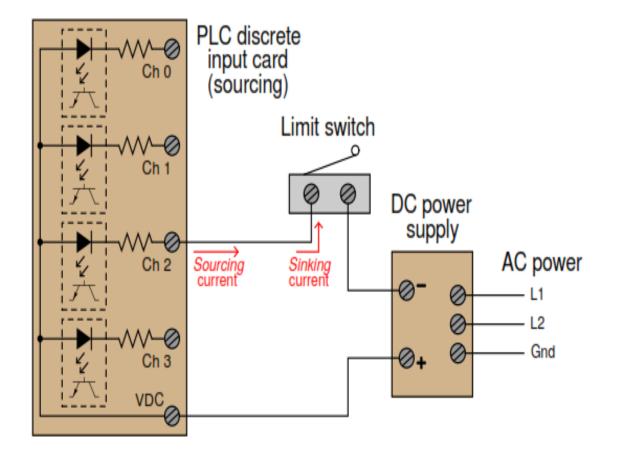
#### **Discrete** I/O PLC Contactor $\odot$ $\odot$ 103 Processor Discrete output card (TRIAC) Power supply Chi $\odot$ $\odot$ $\odot$ Optocoupler Ch2, Z 🖓 🚺 $\frac{Ch3}{2}$ Lamp AC power supply ØL1 ØL2/N VAC Gnd

Setting a bit (1) in the PLC's output register sends a "high" signal to the LED inside the optocoupler, turning on the photo-TRIAC, sending AC power to the output channel to energize the load.

#### Discrete I/O

If the discrete device connecting to the PLC is not polarity-sensitive, either type of PLC I/O module will suffice. For example, the following diagrams show a mechanical limit switch connecting to a sinking PLC input and to a sourcing PLC input:



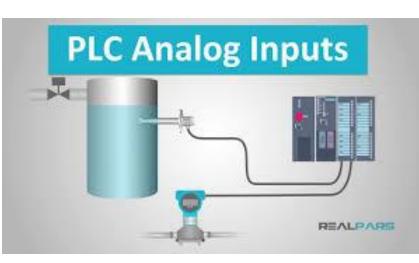


### Analog I/O

All PLCs are digital devices at heart. Thus, in order to interface with an analog sensor or control device, some "translation" is necessary between the analog and digital worlds. Inside every analog input module is an ADC, or Analog-to-Digital Converter, circuit designed to convert an analog electrical signal into a multi-bit binary word. Conversely, every analog output module contains a DAC, or Digital-to-Analog Converter, circuit to convert the PLC's digital command words into analog electrical quantities.

Analog I/O is commonly available for modular PLCs for many different analog signal types, including:

- ✓ Voltage (0 to 10 volt, 0 to 5 volt)
- $\checkmark$  Current (0 to 20 mA, 4 to 20 mA)
- ✓ Thermocouple (millivoltage)
- ✓ RTD (millivoltage)
- ✓ Strain gauge (millivoltage)



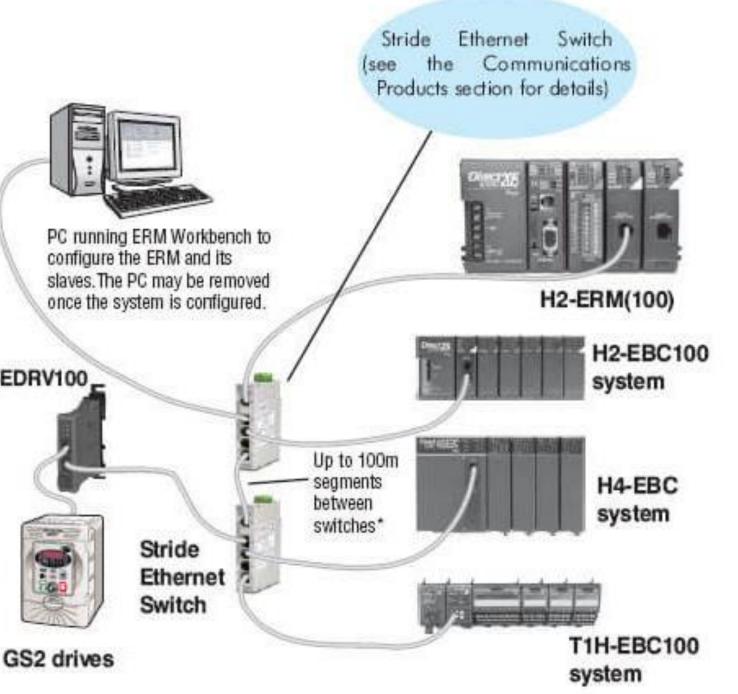


4-O - FBs-4DA - FATEK Automation Corp.

#### Network I/O

• Many different digital network standards exist for PLCs to communicate with, from PLC to PLC and between PLCs and field devices. One of the earliest digital protocols developed for PLC communication was Modbus, originally for the Modicon brand of PLC. Modbus was adopted by other PLC and industrial device manufacturers as *a de facto* standard and remains perhaps the most universal digital protocol available for industrial digital **GS-EDRV100** devices today.

• Another digital network standard developed by a particular manufacturer and later adopted as a de facto standard is Profibus, originally developed by *Siemens*.



## **Special module**

Other types of output modules

- Motion Control Modules
- PID Modules
- BCD/ASCII Modules
- Stepper Motor Control
- Encoder Counter Module
- High Speed Counters
- Motion & Position Control