

Basic Mechatronics Workshop

Module 1: Introduction to Mechatronics

LAB-2 (Practice)

**Basic concepts of control systems
(Pilot & Memory, Sequence, Time Schedule)**

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LAB-2

Basic concepts of control systems

(Pilot & Memory, Sequence, Time Schedule)

Tasks

(Practice)

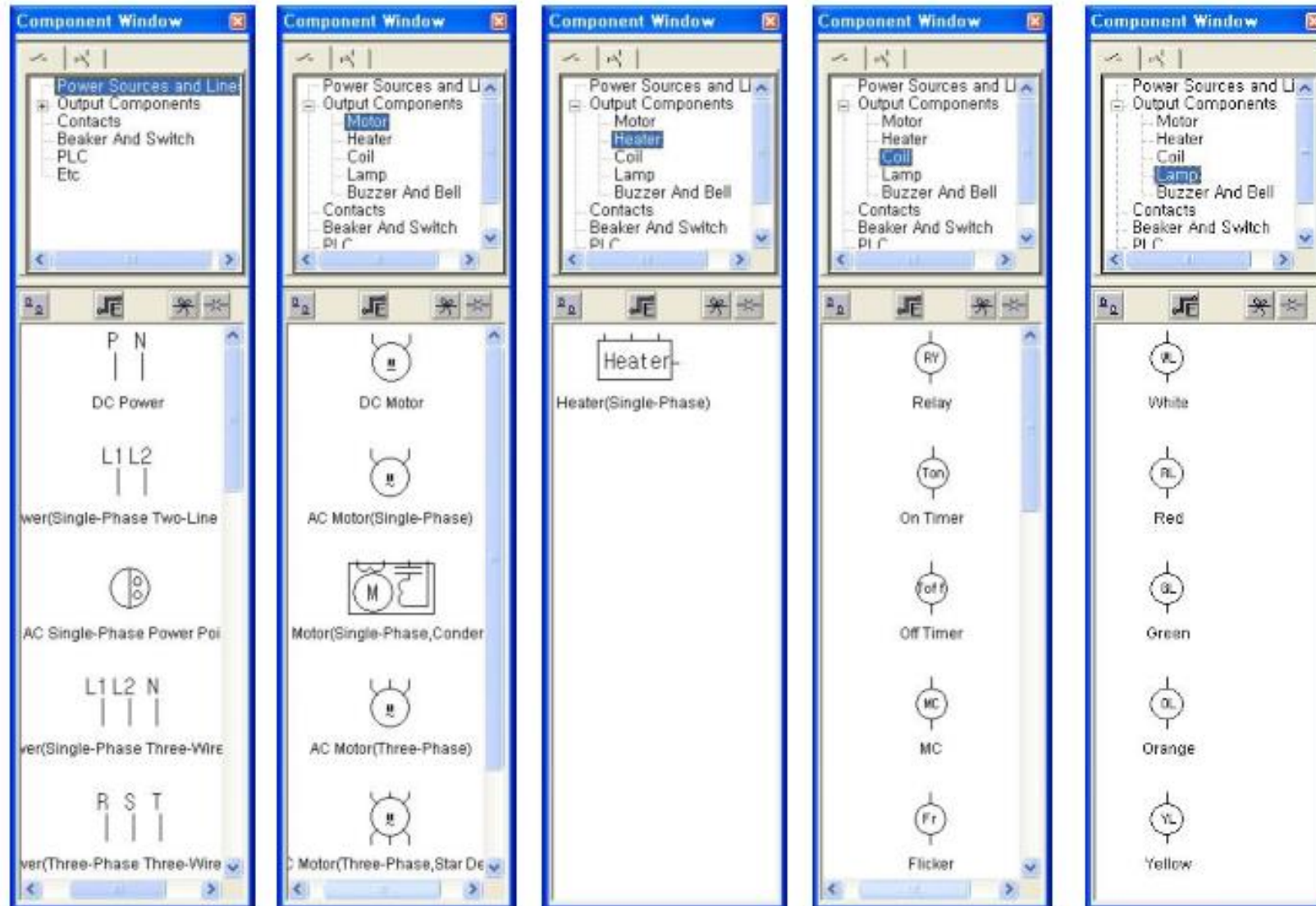
Use ELCO Lab to simulate and implement the following control circuits that explained in Module 1 Chapter 2 .

1. Describe the devices, symbols, and control circuits
2. Design Pilot and Memory control circuits.
3. Describe the operation of a hand-off-automatic control switch.
4. Connect a hand-off-automatic control circuit.
5. Read and interpret sequence control schematics.
6. Convert a sequence control schematic into a wiring diagram.
7. Connect a sequence control circuit.

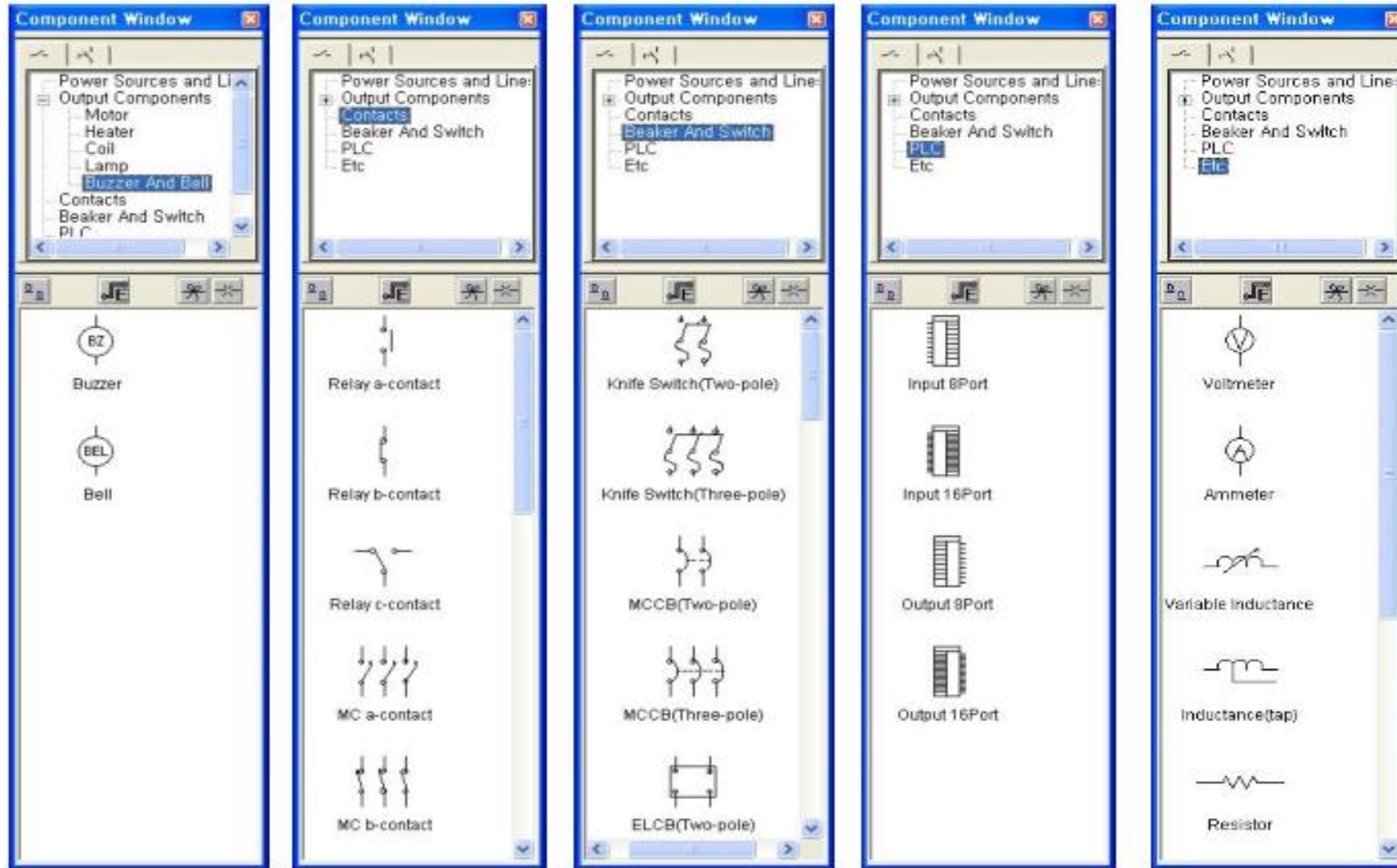
Devices, symbols, and circuits

Electric Sequence Components

⊙ Electric component list(KS)



Electric Sequence Components

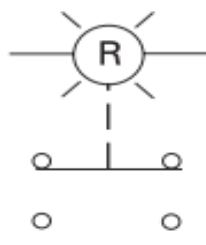


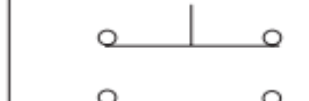


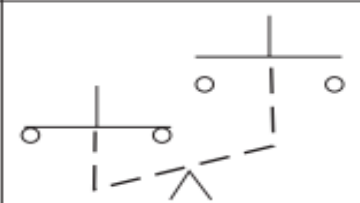
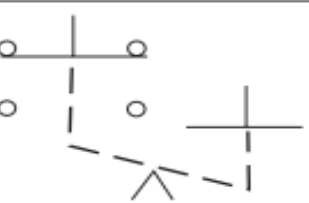


Devices and symbols

Switches																																																							
Disconnect		Circuit Interrupter		Circuit Breaker W/Thermal O.L.		Circuit Breaker W/Magnetic O.L.		Circuit Breaker W/Thermal and Magnetic O.L.																																															
Limit Switches		Foot Switches		Pressure and Vacuum Switches		Liquid Level Switches																																																	
Normally Open	Normally Closed	NO	NC	NO	NC	NO		NO																																															
Held Closed	Held Open	NC	Temperature Actuated Switches		Flow Switches (Air, Water, Etc.)																																																		
Speed (Plugging)		Anti-Plug		Selector																																																			
			2 Position		3 Position		2 Pos. Sel. Pushbutton																																																
			 J K <table border="1" style="display: inline-table; margin-left: 20px;"> <tr><td></td><td>J</td><td>K</td></tr> <tr><td>A1</td><td>X</td><td></td></tr> <tr><td>A2</td><td></td><td>X</td></tr> </table> X - Contact Closed			J	K	A1	X		A2		X	 J K L <table border="1" style="display: inline-table; margin-left: 20px;"> <tr><td></td><td>J</td><td>K</td><td>L</td></tr> <tr><td>A1</td><td>X</td><td></td><td></td></tr> <tr><td>A2</td><td></td><td></td><td>X</td></tr> </table> X - Contact Closed			J	K	L	A1	X			A2			X	 A B <table border="1" style="display: inline-table; margin-left: 20px;"> <tr><th colspan="4">Selector Position</th></tr> <tr><th colspan="2">A</th><th colspan="2">B</th></tr> <tr><th colspan="2">Button</th><th colspan="2">Button</th></tr> <tr><th>Free</th><th>Depres'd</th><th>Free</th><th>Depres'd</th></tr> <tr><td>1-2</td><td>X</td><td></td><td></td></tr> <tr><td>3-4</td><td></td><td>X</td><td>X</td></tr> </table>				Selector Position				A		B		Button		Button		Free	Depres'd	Free	Depres'd	1-2	X			3-4		X	X
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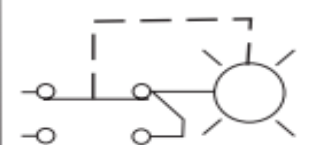


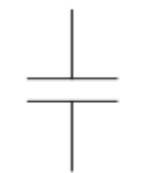
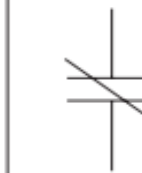

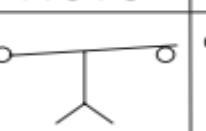
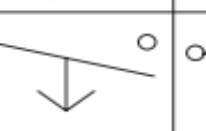
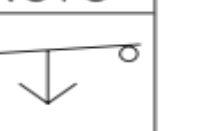
Devices and symbols

Pushbuttons

Momentary Contact				Maintained Contact			Illuminated
Single Circuit		Double Circuit	Mushroom Head	Wobble Stick	Two Single Circuit	One Double Circuit	
NO	NC	NO & NC			Two Single Circuit	One Double Circuit	
							

Pilot Lights

Contacts



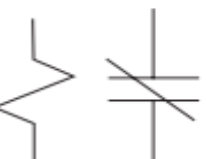


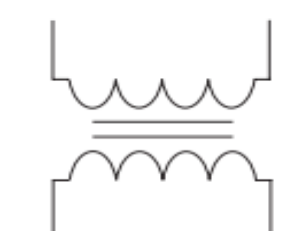





Indicate Color by Letter		Instant Operating				Timed Contacts - Contact Action Retarded After Coil Is:			
Non Push-to-Test	Push-to-Test	With Blowout	Without Blowout	With Blowout	Without Blowout	Energized		Deenergized	
		NO	NC	NO	NC	NOTC	NCTO	NOTO	NCTC
									

Coils

Overload Relays

Inductors




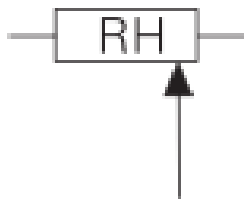
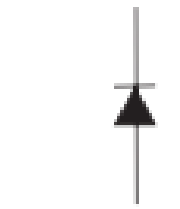
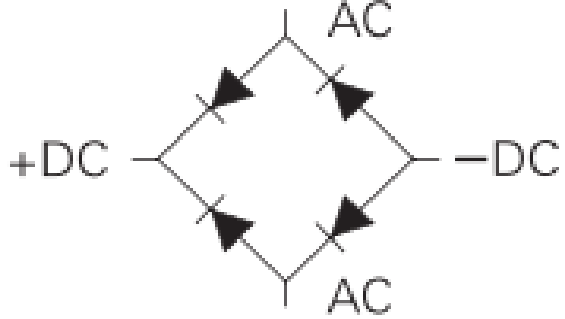
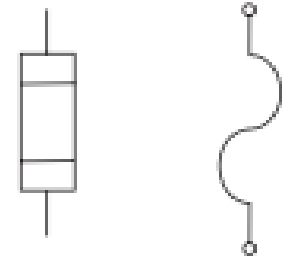





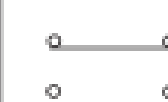
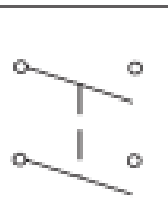
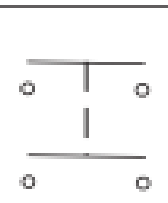
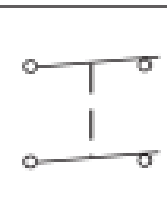
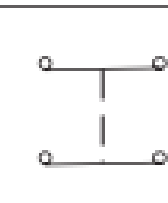
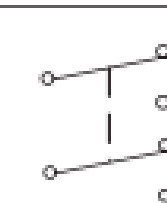
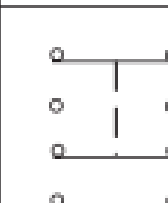
Transformers

Shunt	Thermal	Magnetic	Iron Core	Auto	Iron Core	Air Core	Dual Voltage
							
Series			Air Core	Current			
							

Devices and symbols

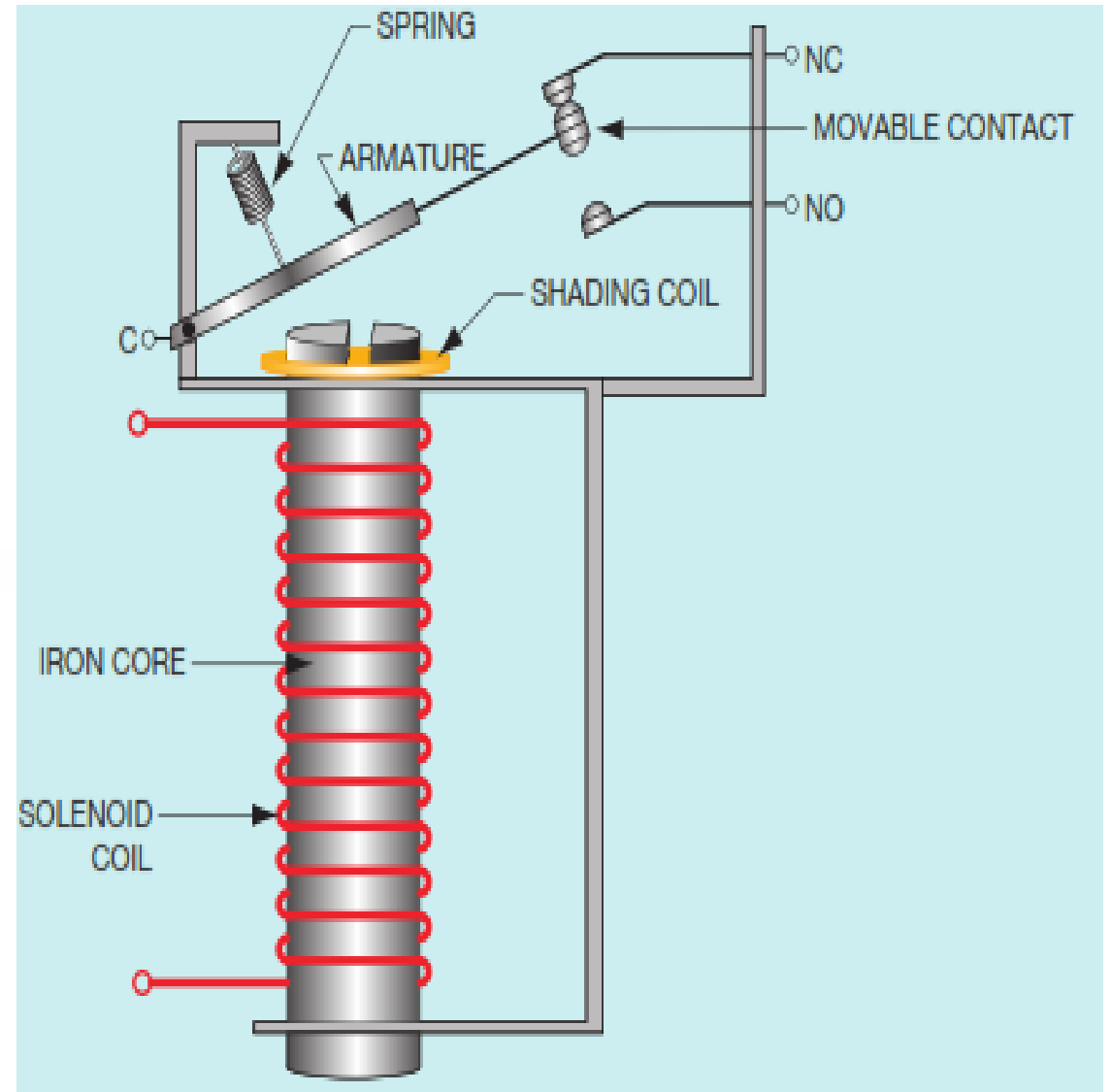
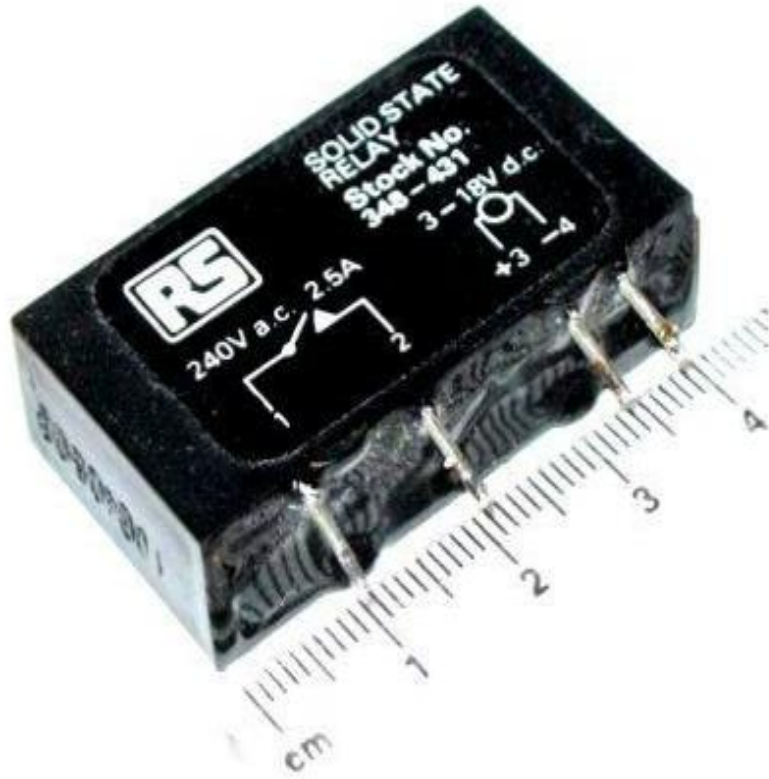
AC Motors				Schematic Wiring			Battery
Single Phase	Three-Phase Squirrel Cage	Wound Rotor	Not Connected	Connected	Power	Control	
DC Motors				Meter	Meter Shunt	Wiring Terminal	Connections Mechanical
Armature	Shunt Field	Series Field	Comm. or Compens. Field	Indicate Type by Letter			
						Ground	
	(Show 4 Loops)	(Show 3 Loops)	(Show 2 Loops)				
Annunciator	Bell	Buzzer	Horn Siren, Etc.		Capacitors		
				Fixed		Adjustable	

Devices and symbols

Resistors				Half Wave Rectifier	Full Wave Rectifier	Fuse
Fixed	Heating Element	Adj. By Fixed Taps	Rheostat Pot Or Adj. Tap			
						
Supplementary Contact Symbols					Terms	
SPST NO		SPST NC		SPDT		
Single Break	Double Break	Single Break	Double Break	Single Break	Double Break	SPST Single-Pole Single-Throw
						SPDT Single-Pole Double-Throw
DPST 2 NO		DPST 2 NC		DPDT		DPST Double-Pole Single-Throw
Single Break	Double Break	Single Break	Double Break	Single Break	Double Break	DPDT Double-Pole Double-Throw
						NO Normally Open
						NC Normally Closed

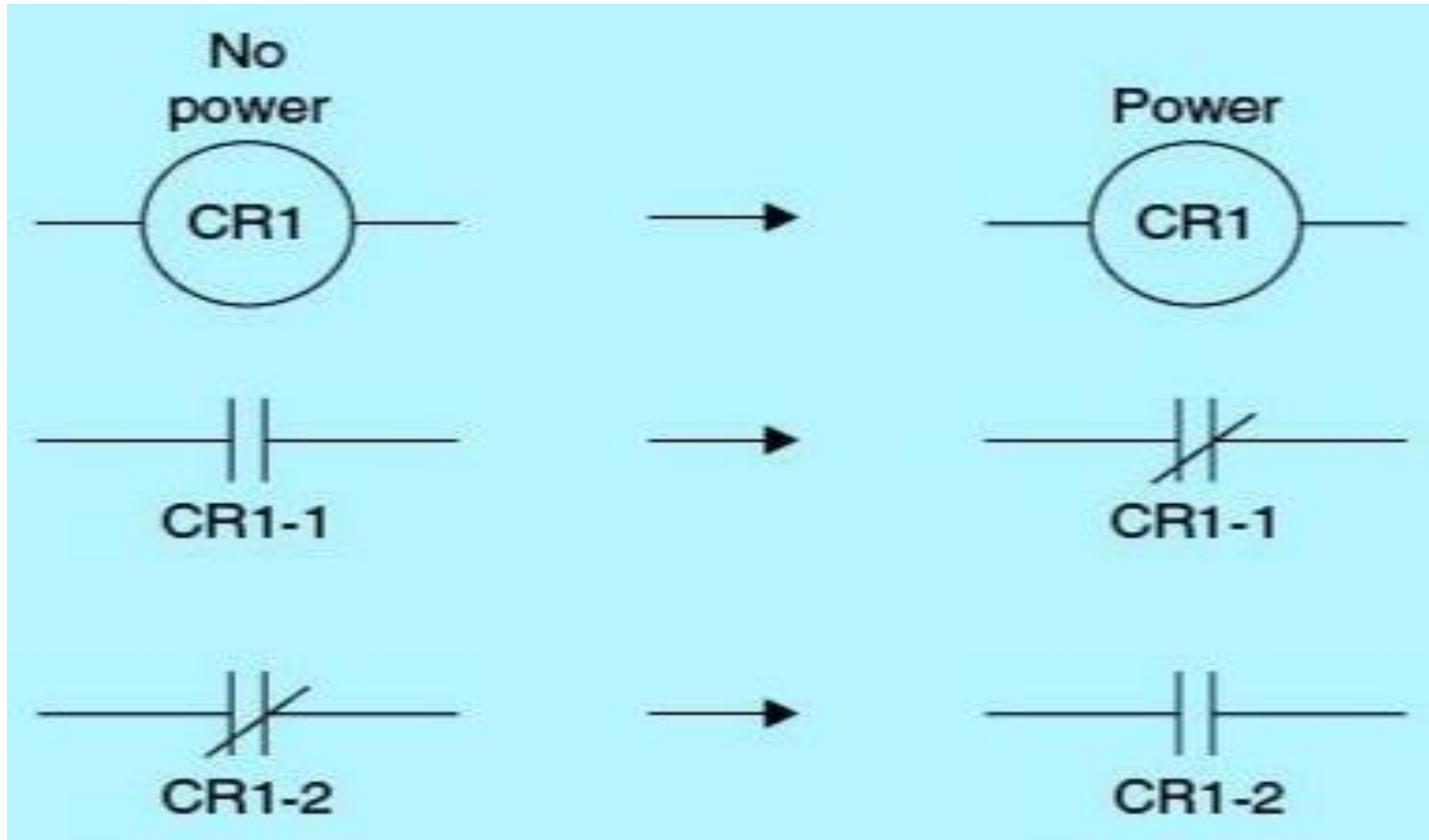
Hard-wired control systems

Conventional Relays



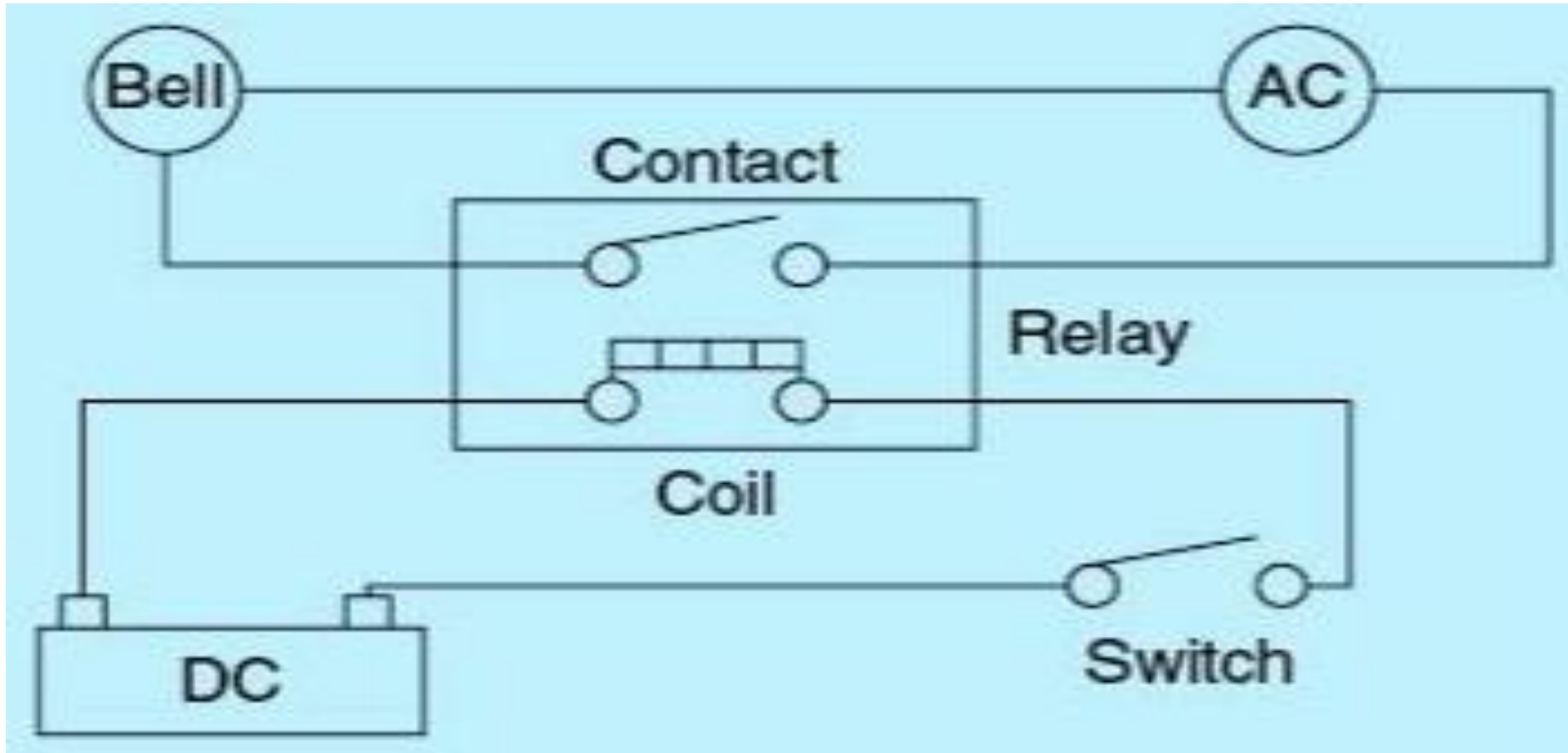
Hard-wired control systems

Conventional Relays



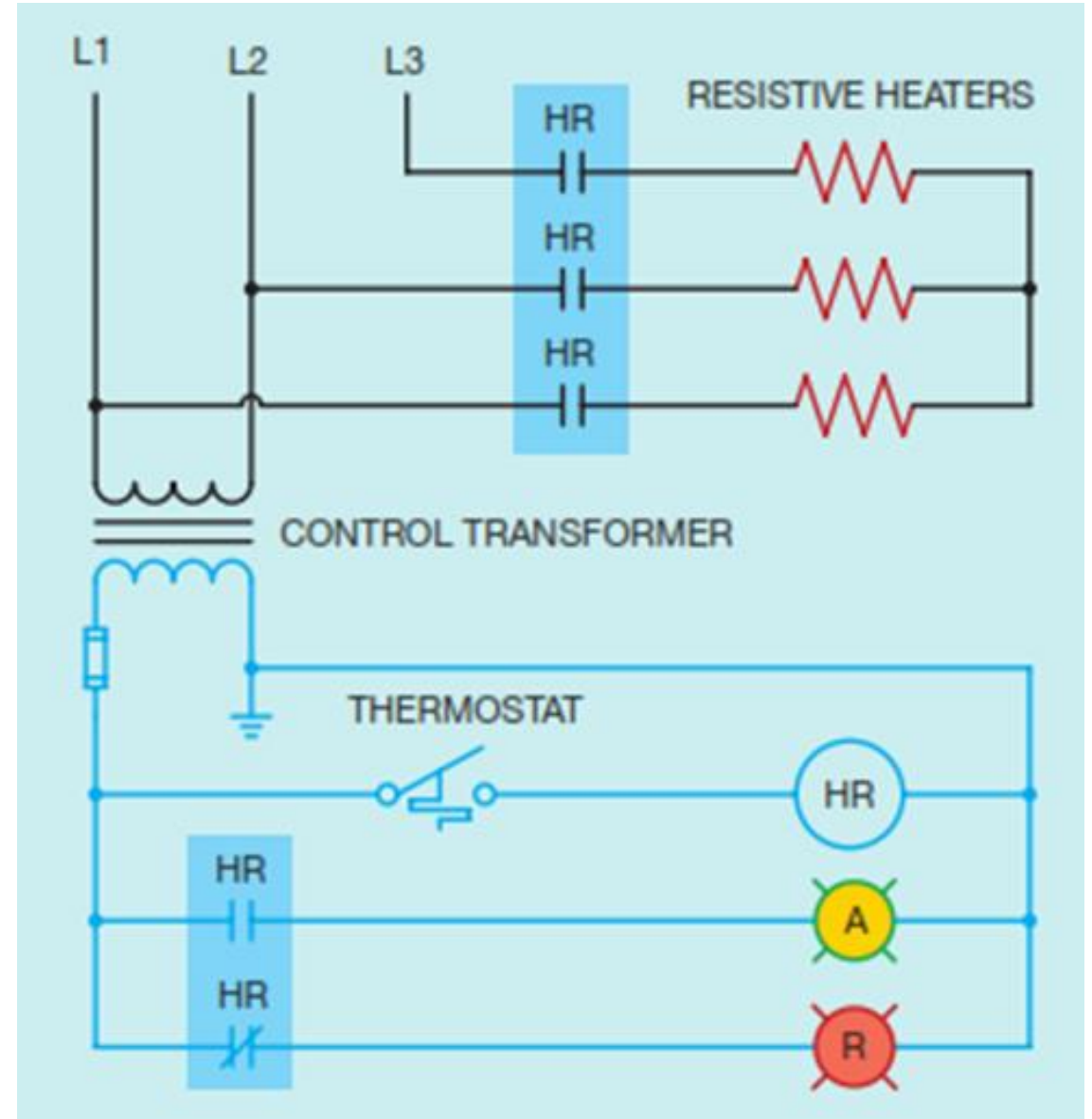
Hard-wired control systems

Simple relay circuit.

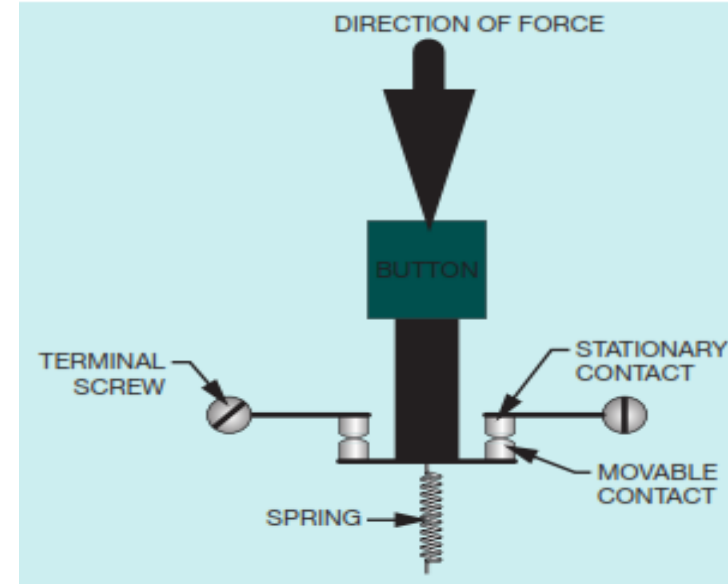
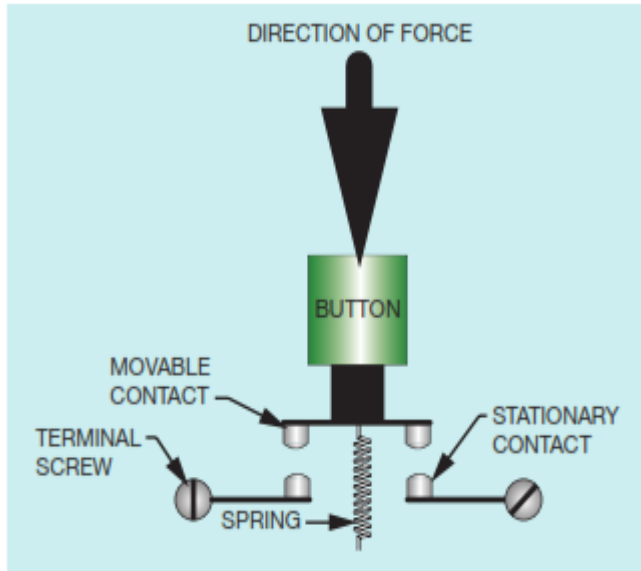


Hard-wired control systems

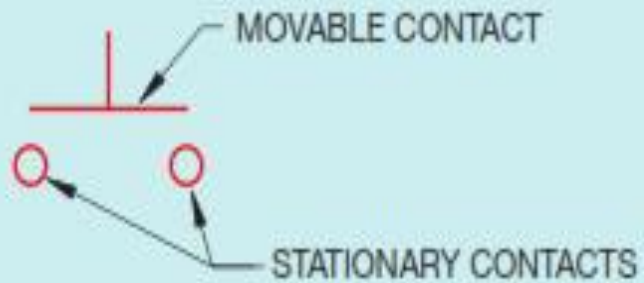
Contactors



Push Buttons

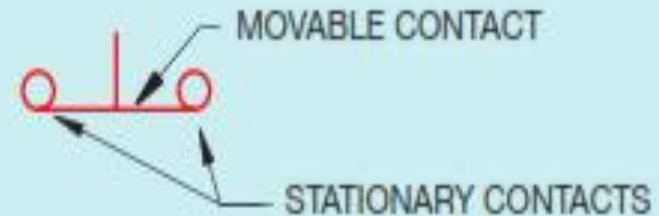


NORMALLY OPEN PUSH BUTTON



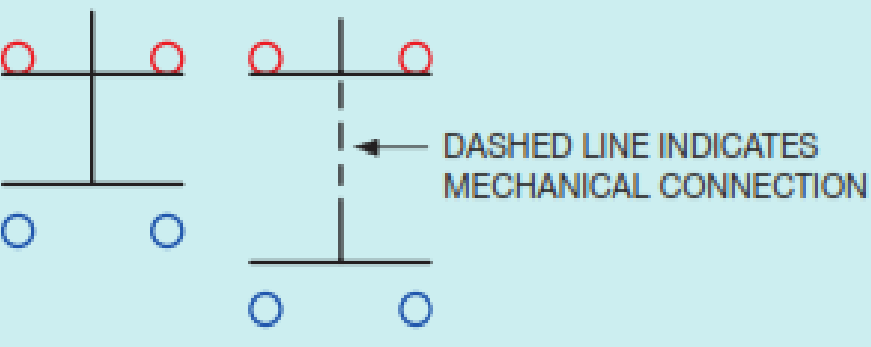
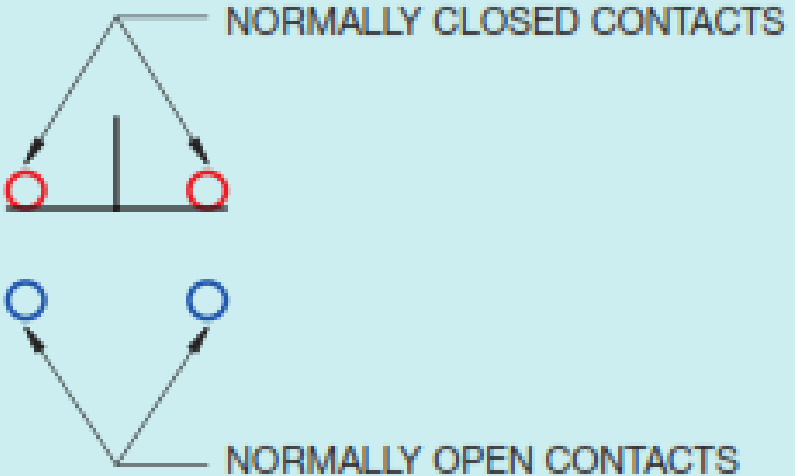
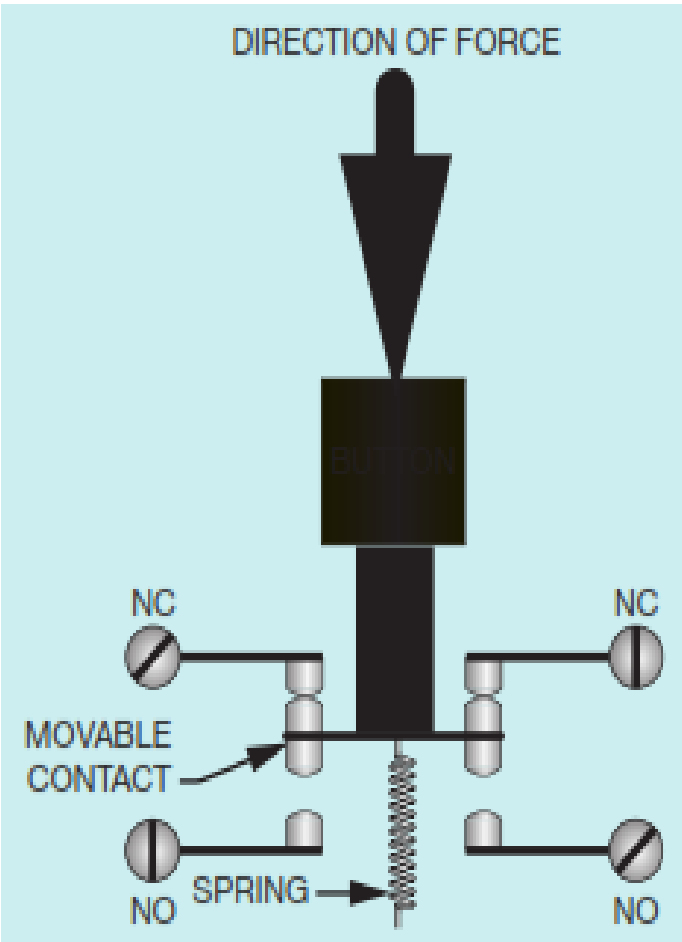
NORMALLY OPEN PUSH BUTTONS ARE DRAWN WITH THE MOVABLE CONTACT ABOVE AND NOT TOUCHING THE STATIONARY CONTACTS.

NORMALLY CLOSED PUSH BUTTON



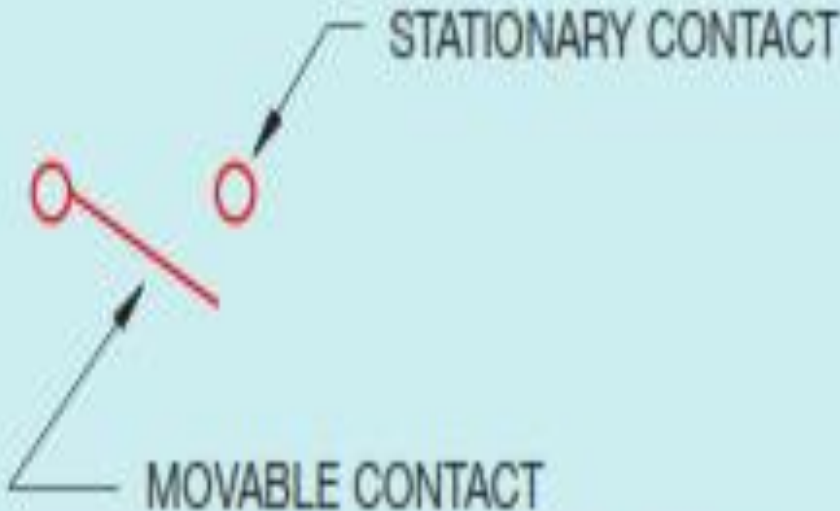
NORMALLY CLOSED PUSH BUTTONS ARE DRAWN WITH THE MOVABLE CONTACT BELOW AND TOUCHING THE STATIONARY CONTACTS.

Double-Acting Push Buttons



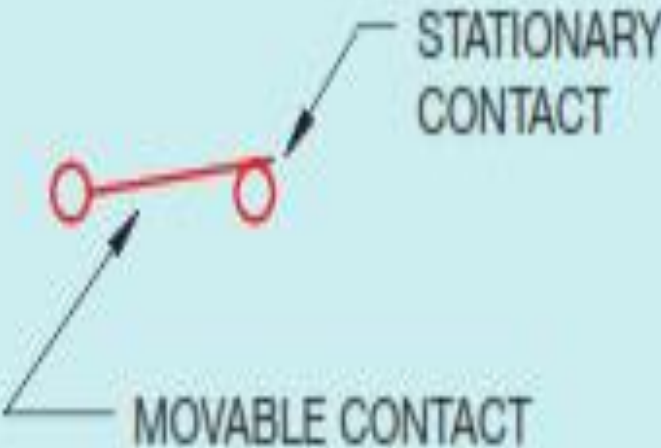
Switch Symbols

NORMALLY OPEN SWITCH



THE MOVABLE CONTACT IS DRAWN BELOW AND NOT TOUCHING THE STATIONARY CONTACT

NORMALLY CLOSED SWITCH



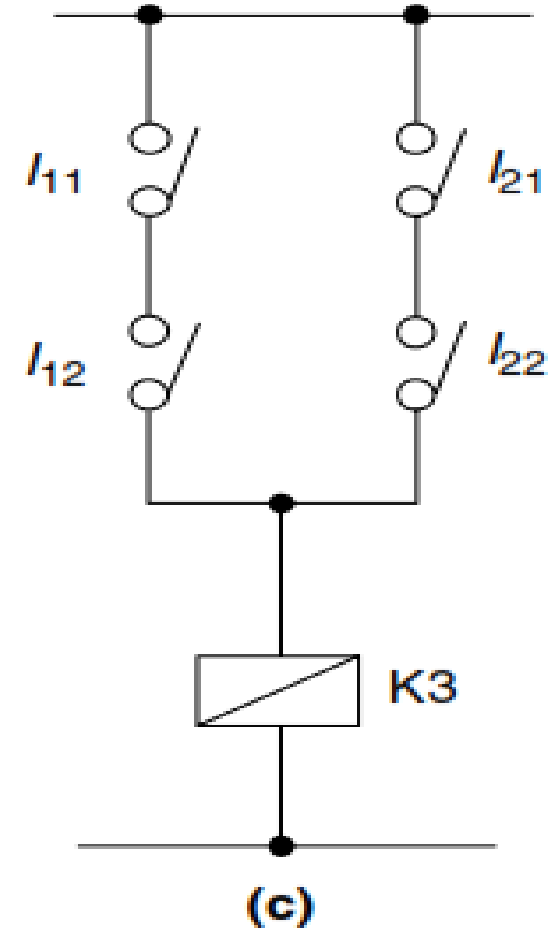
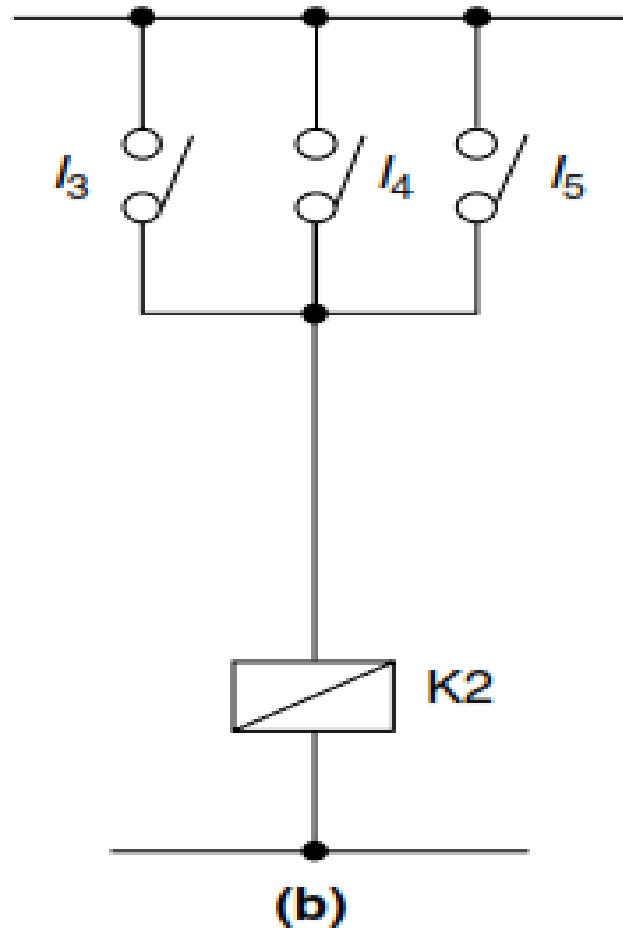
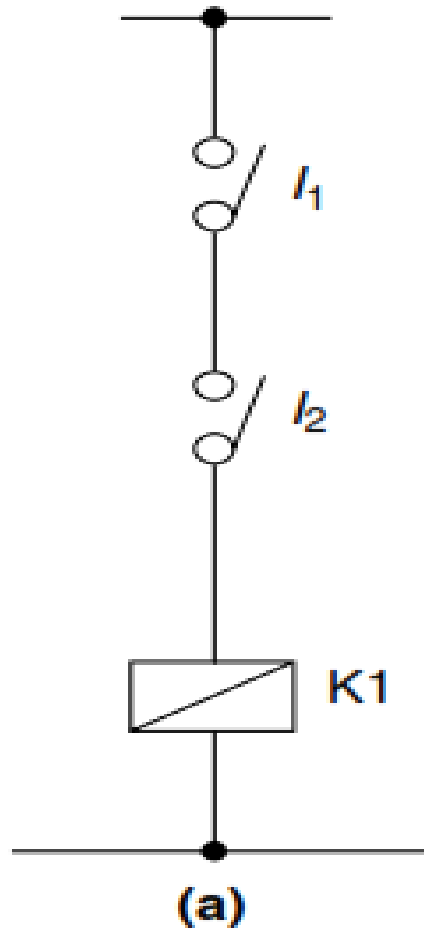
THE MOVABLE CONTACT IS DRAWN ABOVE AND TOUCHING THE STATIONARY CONTACT

Hard wired control systems consist of three division

1. **Input section** – Consists of pushbuttons, switches and sensors. They transfer signals to the processing section
2. **Processing section** –Consists of relay coils and contacts. They determined the relationship between the inputs received and outputs required
3. **Output section** –Consists of solenoids, lamps, and contactor coils etc. The processed signals are transferred to this section.

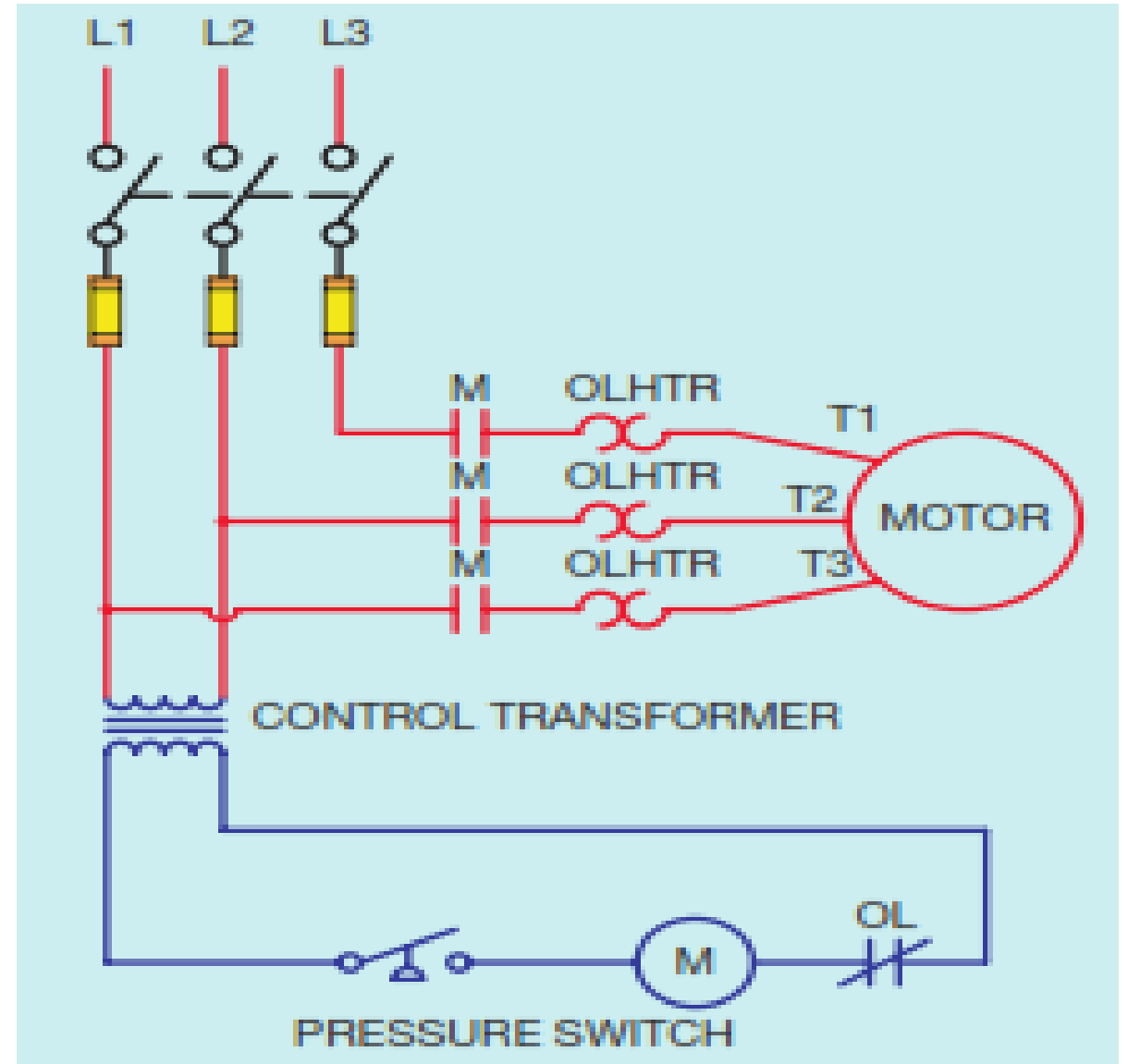
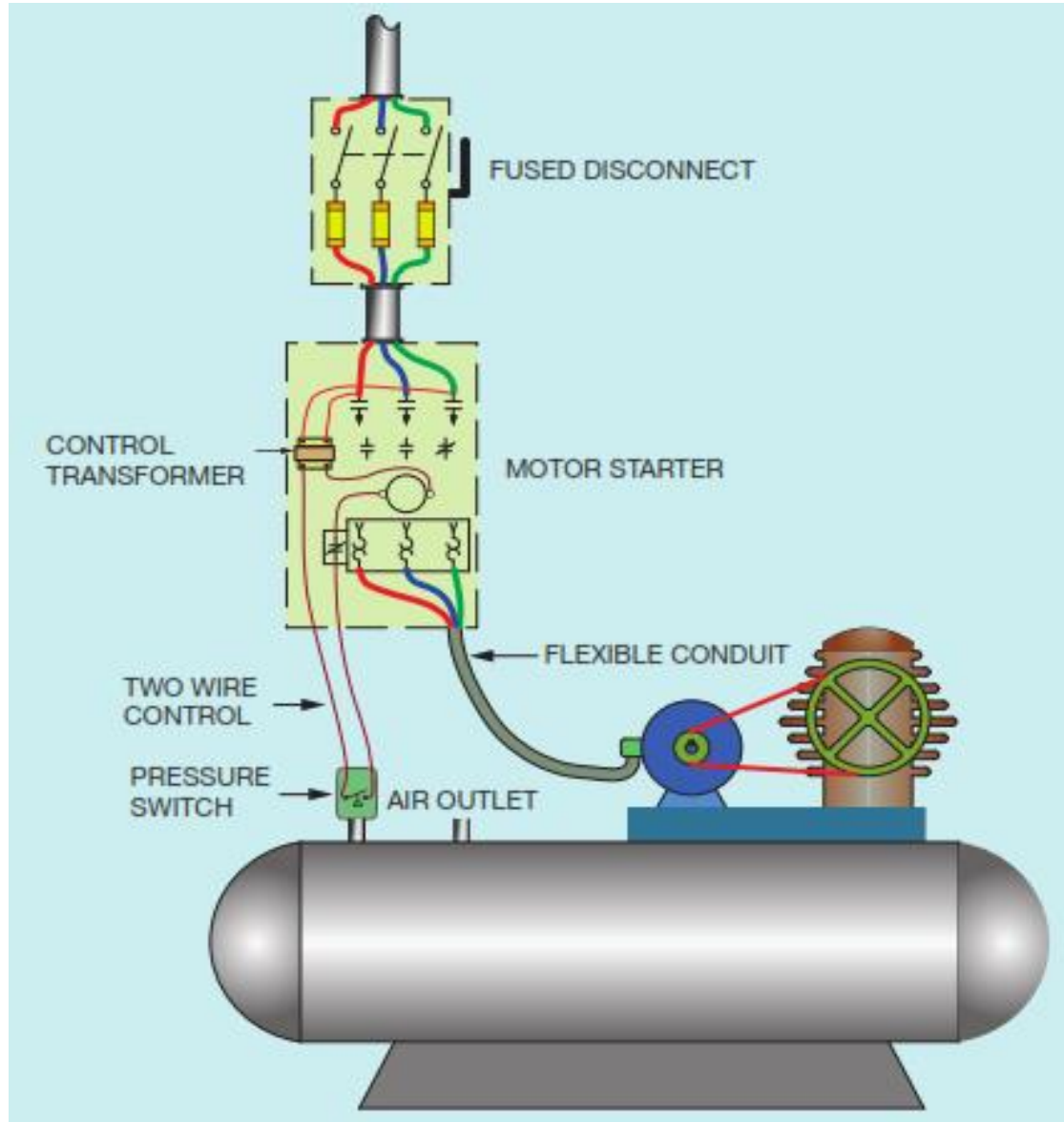
Hard-wired control systems

Simple control circuits



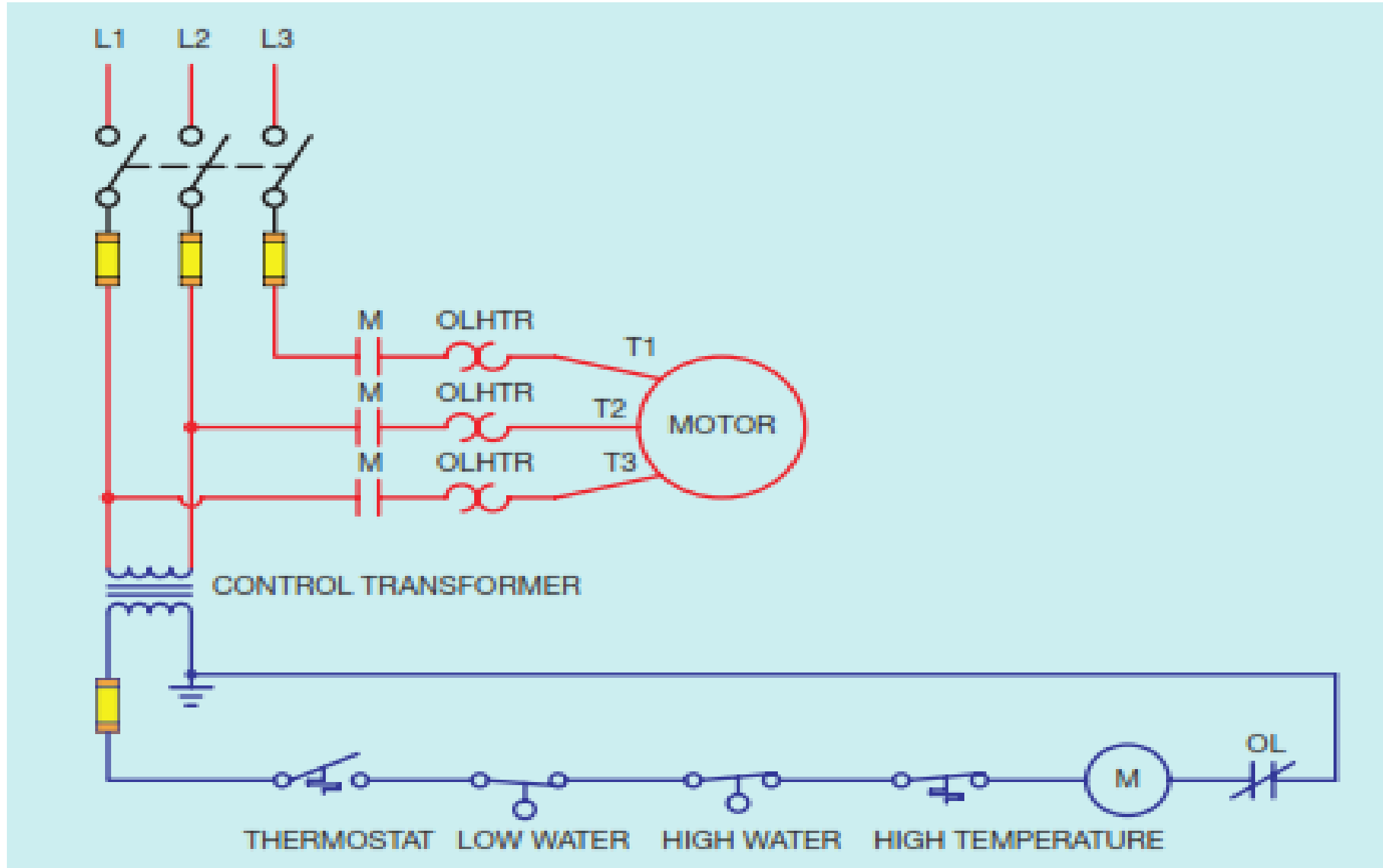
Basic Control Circuits

The motor starter is controlled by running two wires to a pressure switch.

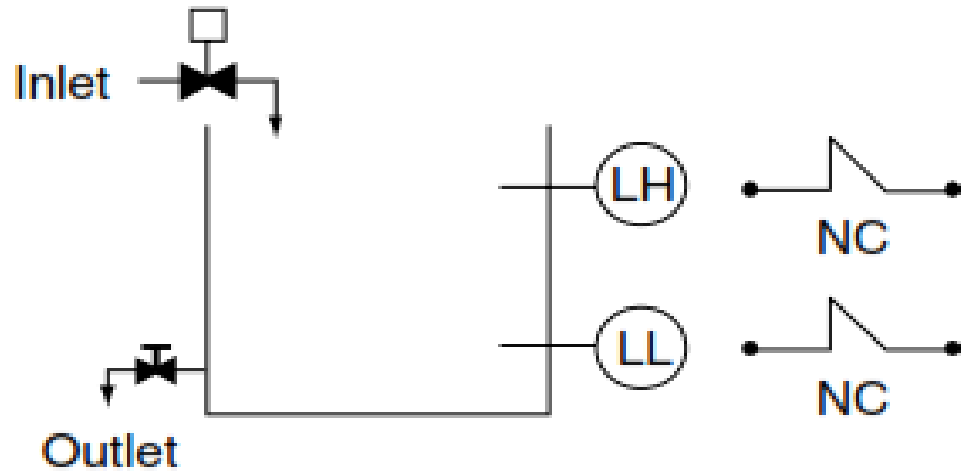


Basic Control Circuits

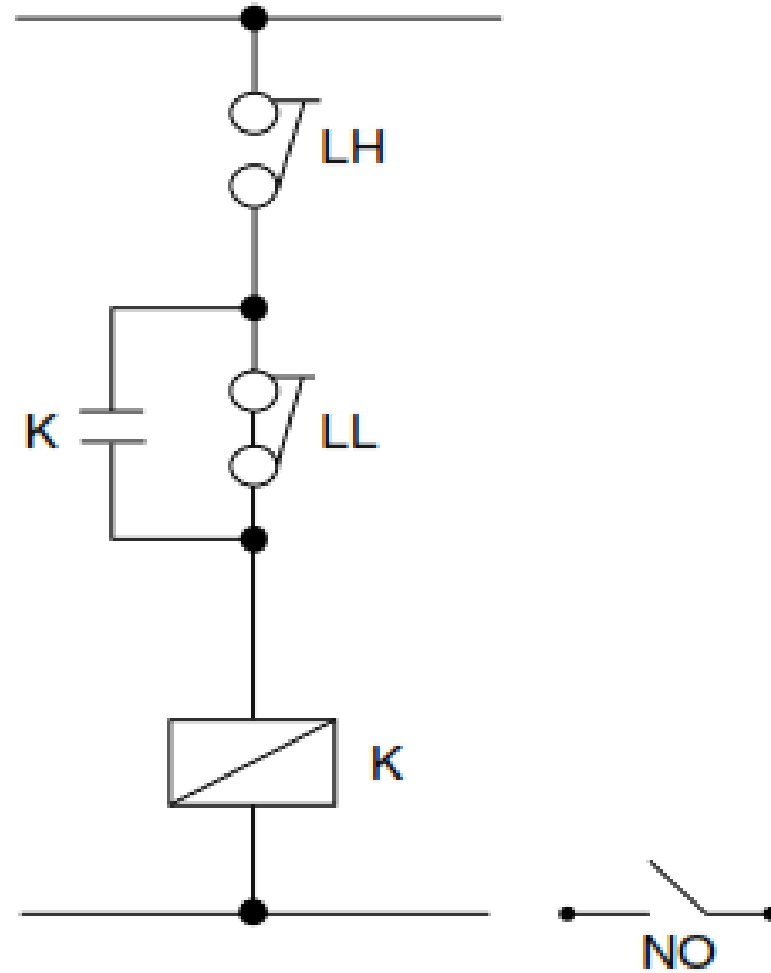
Two-wire control circuits may contain any number of external sensing devices.



Example of simple control circuit for water tank inlet valve operation



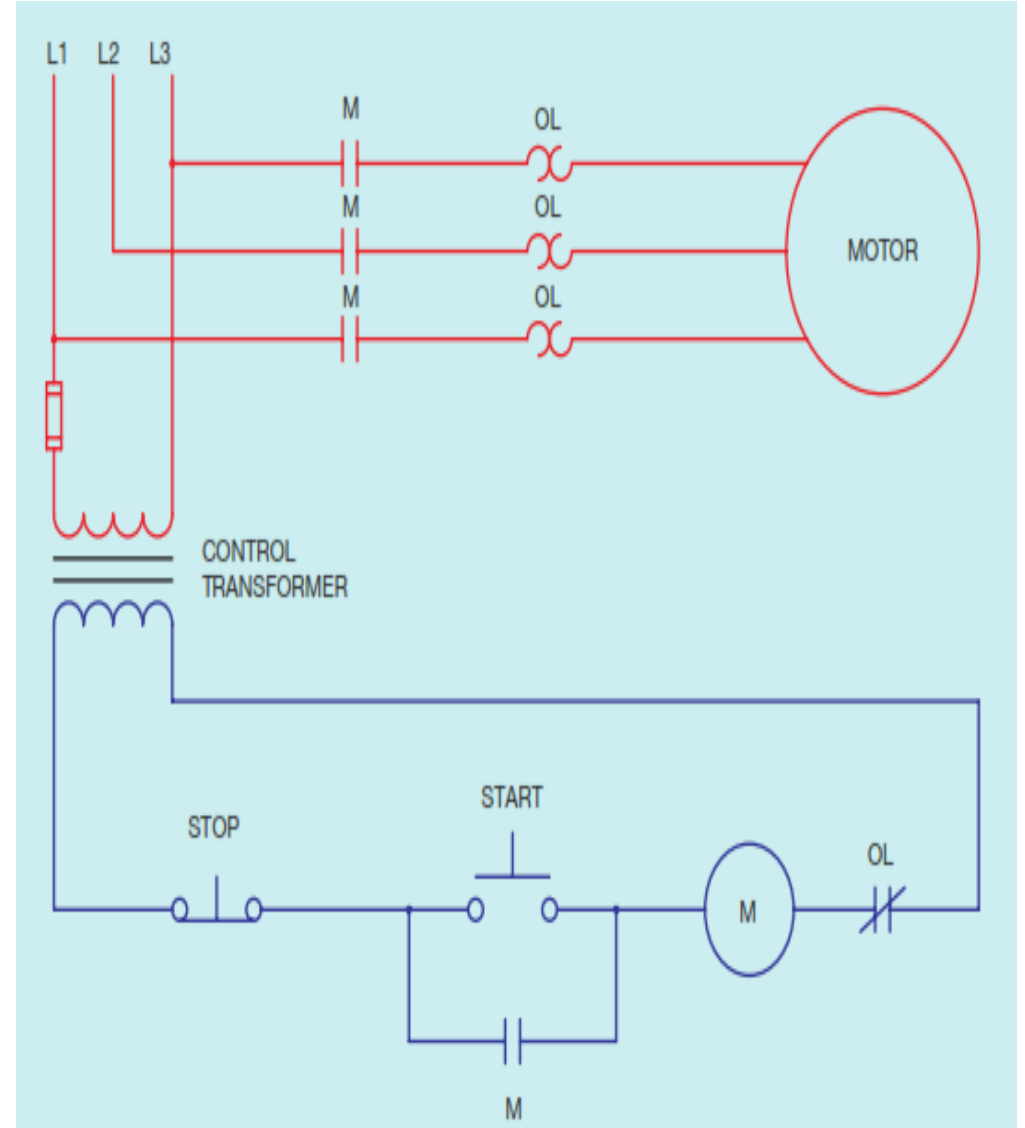
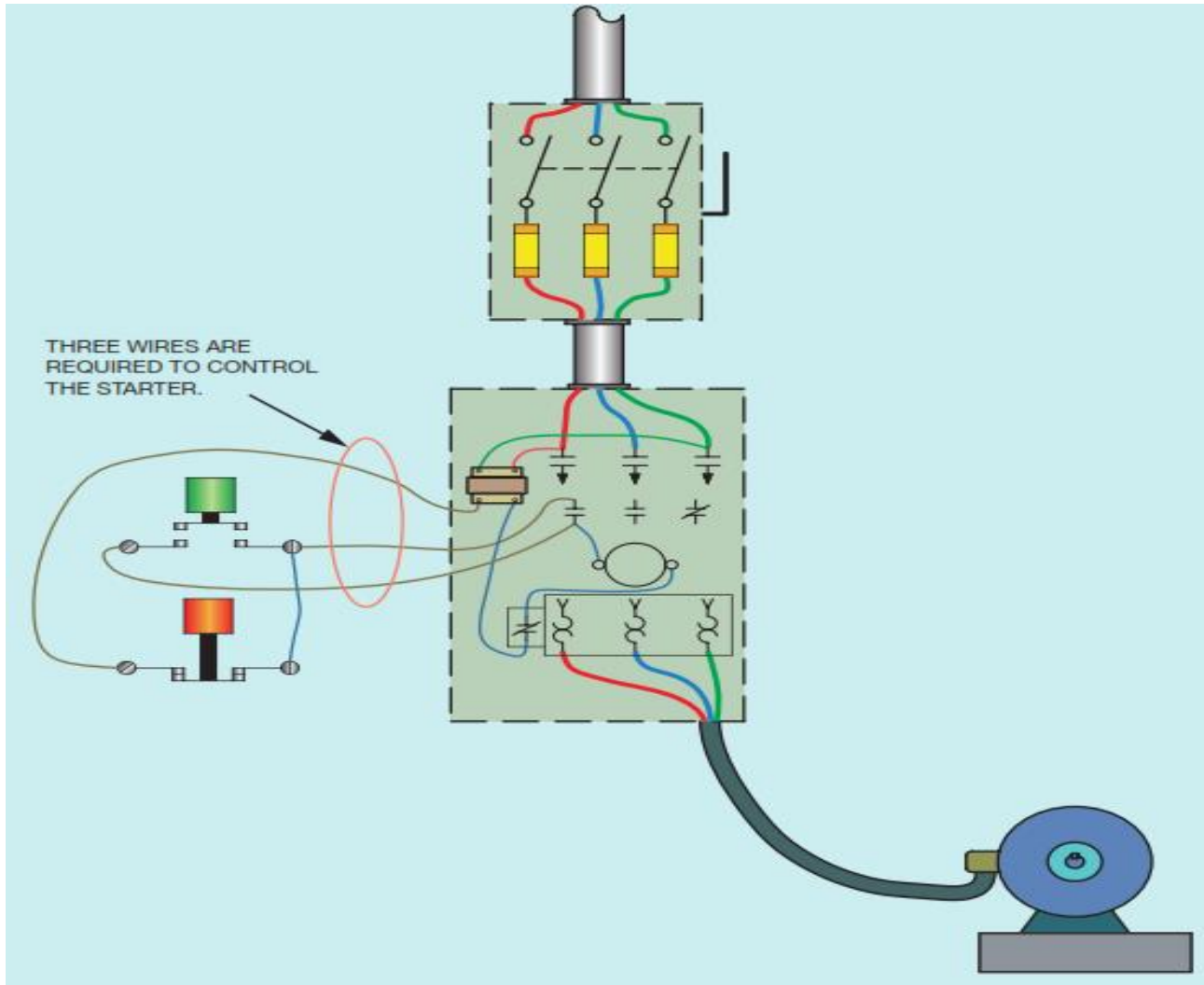
Assume: both LH & LL as NC
(when level is below switch)



Same NO contact is used to drive the inlet relay coil

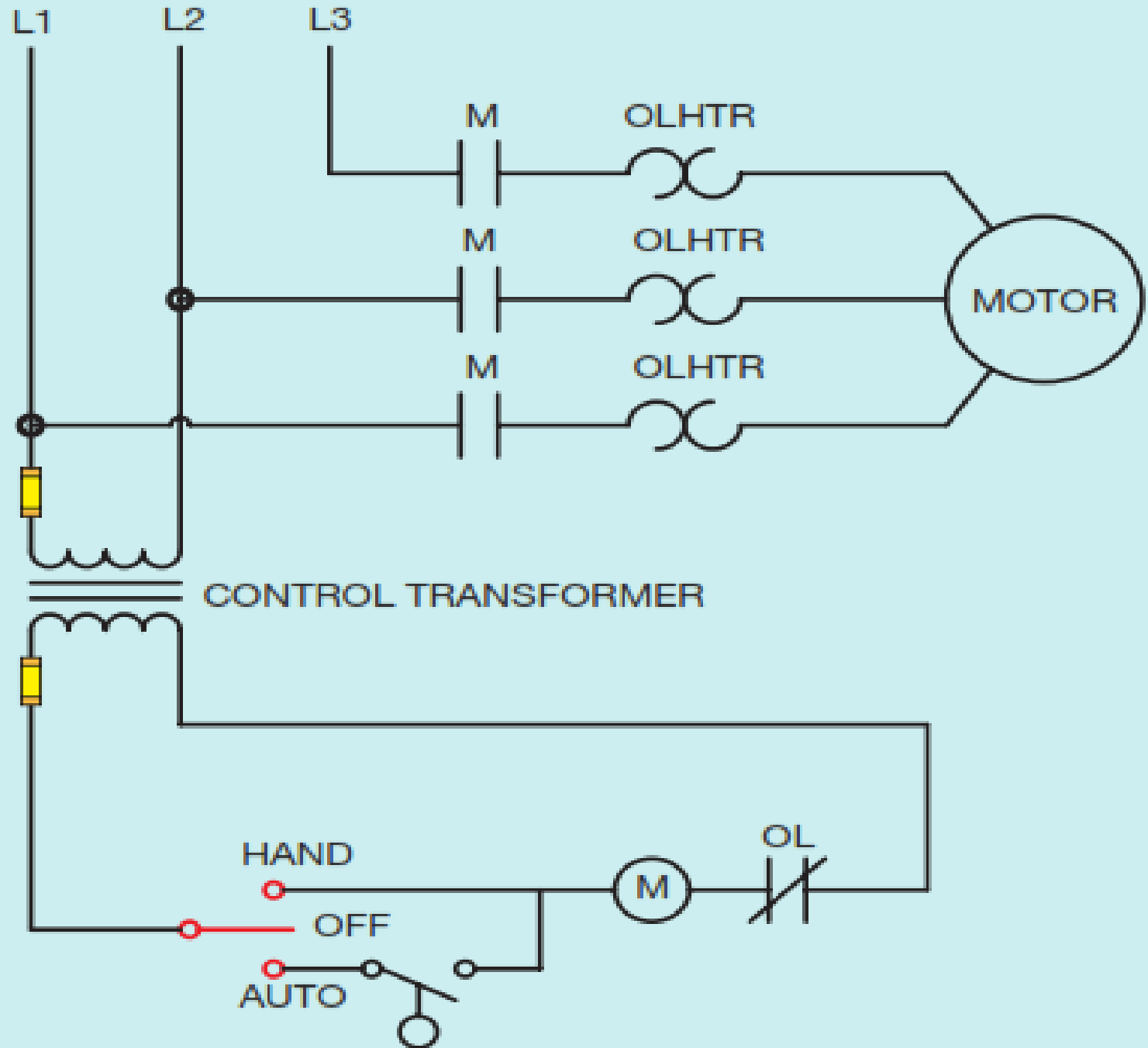
Basic Control Circuits

Three wires are required to control a starter with momentary contact devices, such as push buttons.



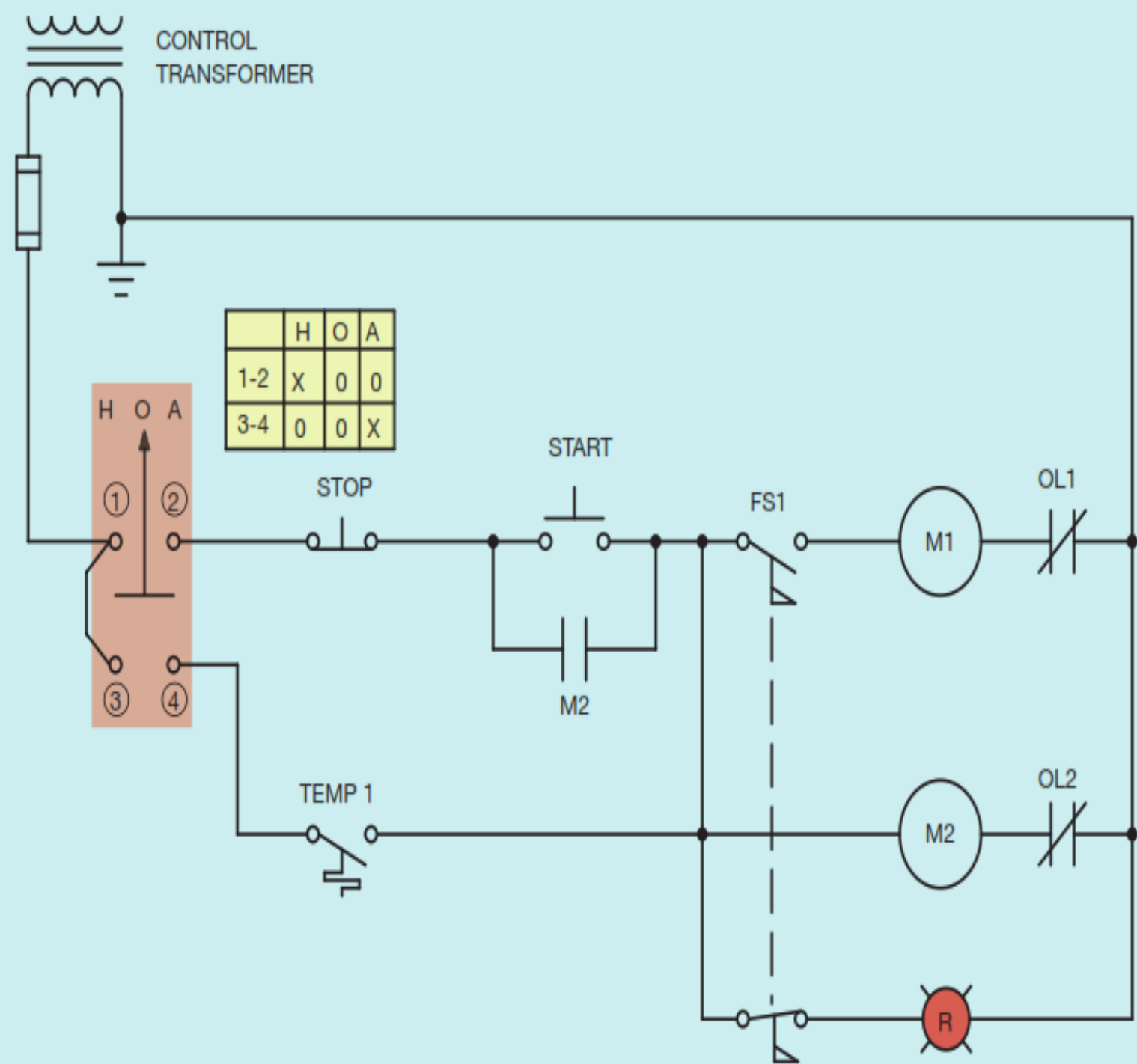
Hand-Off-Automatic Controls

Hand-off-automatic switch provides manual control of a motor, or control can be provided by a float switch.



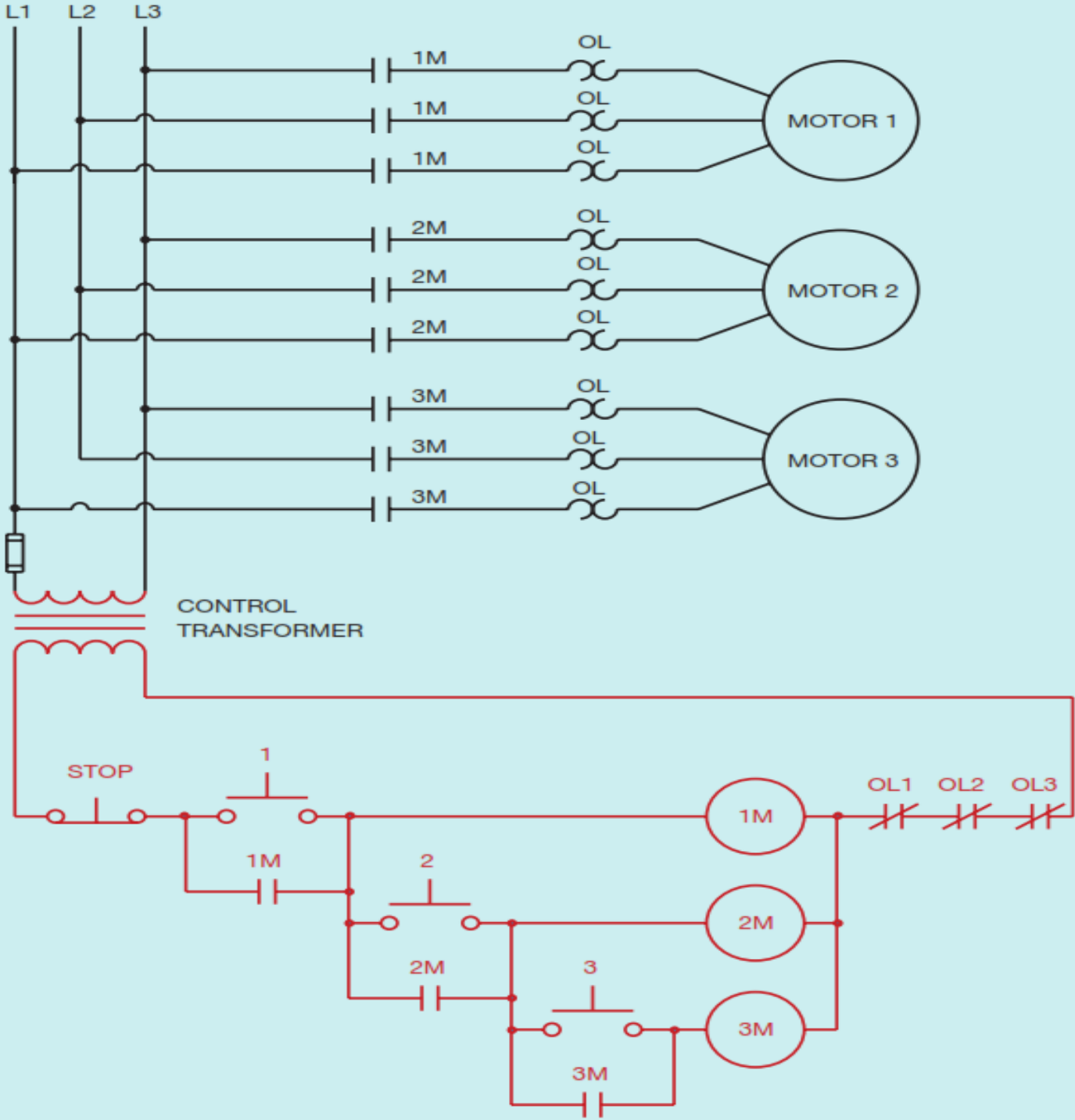
Hand-Off-Automatic Controls

A water-cooled motor must have a flow of water before it is permitted to run.



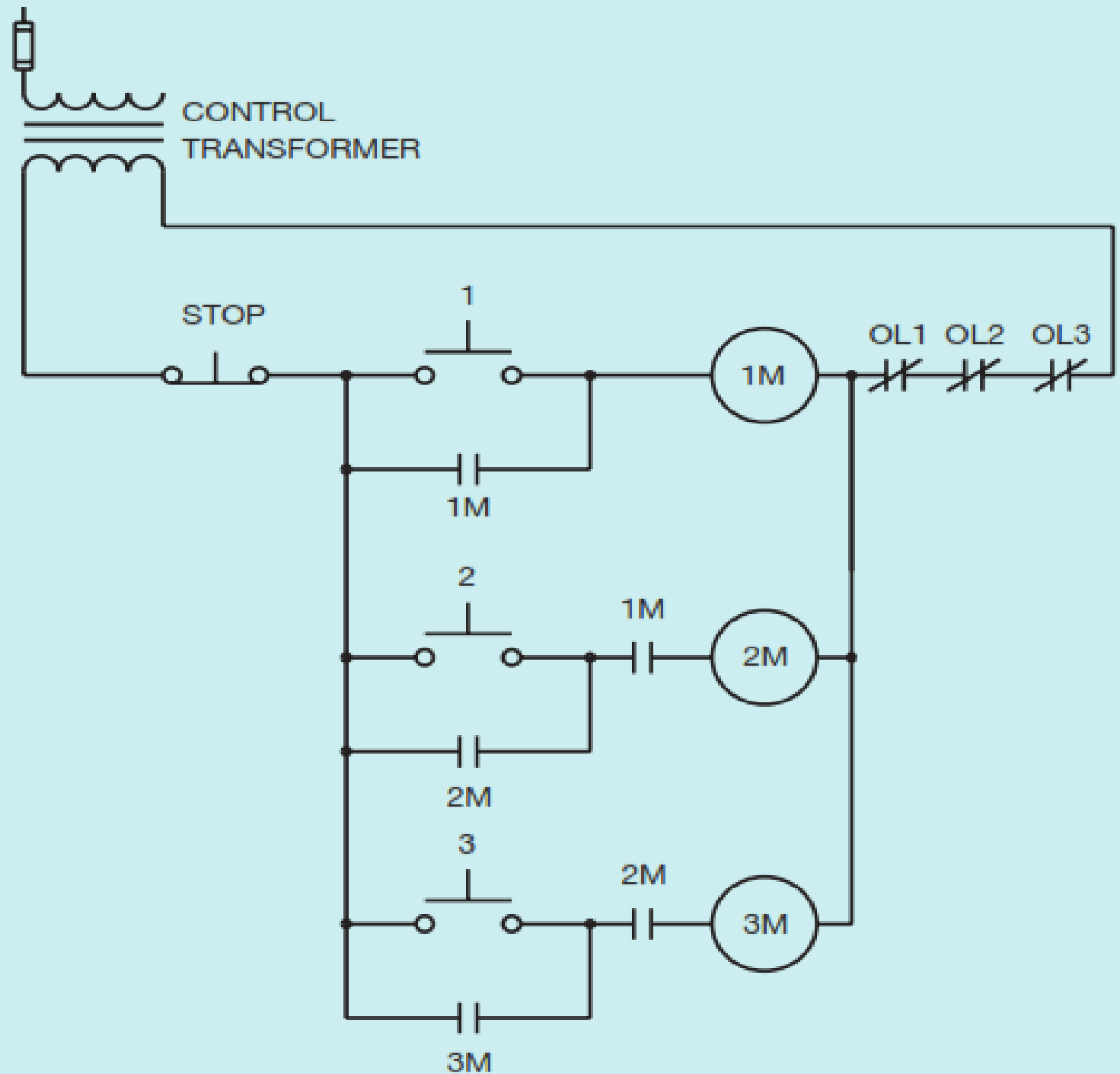
Sequence control

One example of a circuit that provides sequence control.



Sequence control

A second circuit for sequence control.



Sequence control

A third circuit for sequence control.

